

- Autonomous navigation Fully automated environmental sampling
- Intelligent charging system Wireless charging station
- Multi-task scheduling Unattended operation
- Environmental Monitoring Interface with different sampling modules

<sup>\*</sup> EMC Robots are shown with APC and Remote Particle Sensor modules

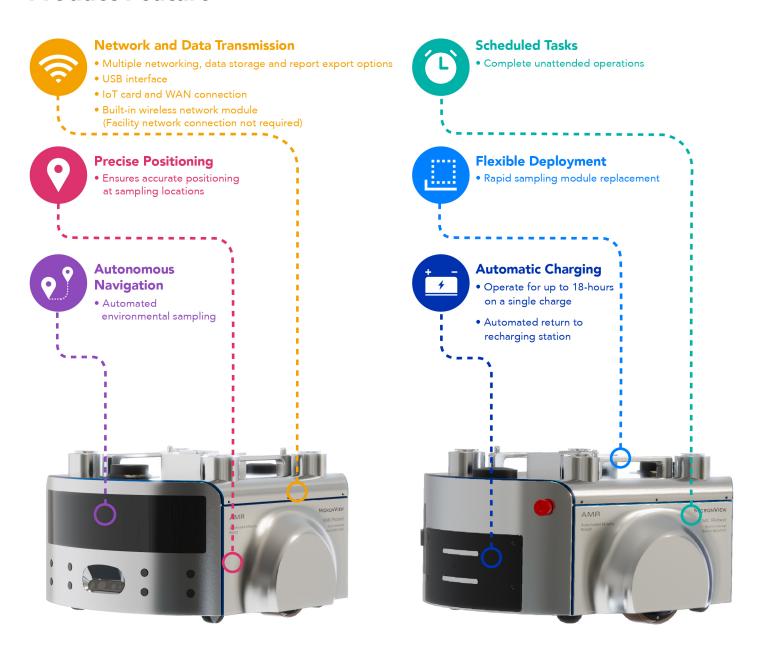
<sup>\*</sup> Compatible with BAMS and VHP modules

## **Product Introduction**

The Environmental Monitor & Control Robot (EMC Robot) enables the automated sampling of cleanroom environments using a SLAM\* algorithm and LiDAR to ensure accurate site arrival and object avoidance.

The unit can traverse designated areas, automatically open and close doors, autonomously ride elevators, and automatically return to home base for charging. Through automated sampling, the environmental impact of operators and potential for human error can be minimized.

## **Product Feature**



<sup>\*</sup>SLAM is an acronym for Simultabeous Localization And Mapping, which supports localization and map construction for EMC Robots in unknown environments.

## **Product Application**

The EMC Robot is compatible with the portable Aerosol Particle Counter (APC) and Remote Particle Sensor modules. With the particle counting module attached, the robot will automatically arrive at user defined locations and complete sampling according to a set sampling scheme. The unit's automated navigation and sampling lower the risk of contamination by reducing human presence in critical areas, and reduce the potential for error in sampling location and time. Resource allocation can also be optimized by automating routine functions and assigning personnel to other critical tasks.

The APC Robot can realize remote sample control and central data management, ensuring continuous real-time monitoring and data storage in dynamic and challenging manufacturing environments. All detection data is stored on the robot's monitoring management system, and data can be uploaded to the specified server or cloud via WIFI/LTE network according to customer requirements. The EMC Robot can also be equipped with a temperature and humidity sensor to collect and store ambient temperature and humidity information.





# **Specification Sheet**

Specification		Environmental Monitor & Control Robot Base	
Mass and Volume	Diameter	608mm	
	Height	306mm	
	Net weight	30kg	
	Maximum load	40kg	
Battery performance	Battery capacity	960Wh (24V)	
	Working power	50W (With full power, it can work continuously for 18h)	
	Charging time	4h (100-240 VAC, 5A)	
	Battery life	> 3 years (Discharge capacity not less than 60% of initial capacity)	
Material	Chassis	316L stainless steel	
	Wheels	Polyurethane	
Cleaning		Sealed chassis, resists corrosivity of disinfectant wiping	
Maximum map area		500m×500m	
Ground resolution		5cm	
Vehicle performance	Cruising speed	0.5m/s (Modifiable, up to 1.2m/s)	
	Passable width	710mm	

Constituent on	Functional Module Parameters			
Specification	Portable Aerosol Particle Counter	Remote Particle Sensor		
Flow rate	100LPM±3%; 50LPM±3%; 28.3LPM±3%	28.3LPM±3%		
Power	AC 48W; AC 36W; AC 34W	AC 40W		
Sample quantity	Not restricted(In liters)	N/A		
Sampling cycles	Not restricted	N/A		
Sampling interval	Not restricted (In seconds)	N/A		
Sampling delay	Not restricted (In seconds)	N/A		
Other parameters	For detailed performance parameters, see functional module specification document.			

# **Ordering Information**

Name	Model	Order No.
Environmental Monitor & Control Robot Base   EMC Robot Base	S1101	MACHS1101
Aerosol Particle Counter Robot   APC Robot	SA110	MACHSA110
Aerosol Particle Counter Robot   APC Robot	SA5101	MACHSA5101

<sup>\*</sup> SA110= Portable Aerosol Particle Counter module; SA5101=Remote Particle Sensor module

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Version: 1.0

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